

Ergänzungen zur Vorlesung
Kanonische Formulierung der ART

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Hodge-Duality

1 Exterior product and algebra

Let V be a real n -dimensional vector space, V^* its dual space and $T^p V^* = V^* \otimes \cdots \otimes V^*$ its p -fold tensor product. We will follow standard tradition to define *forms*, i.e. the antisymmetric tensor product on the dual vector space V^* rather than on V . Clearly, all constructions that are to follow could likewise be made in terms of V rather than V^* .

$T^p V^*$ carries a representation π_p of S_p , the symmetric group (permutation group) of p objects, given by

$$\pi_p : S_p \rightarrow \text{End}(T^p V^*), \quad \pi_p(\sigma)(\alpha_1 \otimes \cdots \otimes \alpha_p) := \alpha_{\sigma(1)} \otimes \cdots \otimes \alpha_{\sigma(p)} \quad (1)$$

and linear extension to sums of tensor products. On $T^p V^*$ we define the linear operator of antisymmetrisation by

$$\text{Alt}_p := \frac{1}{p!} \sum_{\sigma \in S_p} \text{sign}(\sigma) \pi_p, \quad (2)$$

where $\text{sign} : S_p \rightarrow \{1, -1\} \cong \mathbb{Z}_2$ is the sign-homomorphism. This linear operator is idempotent (i.e. a projection operator) and its image of $T^p V^*$ under Alt_p is the subspace of totally antisymmetric tensor-products. We write

$$\pi_p(T^p V^*) =: \bigwedge^p V^*. \quad (3)$$

Clearly

$$\dim \left(\bigwedge^p V^* \right) = \begin{cases} \binom{n}{p} & \text{for } p \leq n, \\ 0 & \text{for } p > n. \end{cases} \quad (4)$$

We set

$$\bigwedge V^* := \bigoplus_{p=0}^n \bigwedge^p V^*. \quad (5)$$

Let $\alpha \in \bigwedge^p V^*$ and $\beta \in \bigwedge^q V^*$, then we define their antisymmetric tensor product

$$\alpha \wedge \beta := \frac{(p+q)!}{p!q!} \text{Alt}_{p+q}(\alpha \otimes \beta) \in \bigwedge^{p+q} V^*. \quad (6)$$

One easily sees that

$$\alpha \wedge \beta = (-1)^{pq} \beta \wedge \alpha. \quad (7)$$

Bilinear extension of \wedge to all of $\wedge V^*$ endows it with the structure of a real 2^n -dimensional associative algebra, the so-called exterior algebra over V^* . If $\alpha_1, \dots, \alpha_p$ are in V^* , we have

$$\alpha_1 \wedge \dots \wedge \alpha_p = \sum_{\sigma \in S_p} \text{sign}(\sigma) \alpha_{\sigma(1)} \otimes \dots \otimes \alpha_{\sigma(p)}, \quad (8)$$

as one easily shows from (6) and (7) using induction.

If $\{\theta^1, \dots, \theta^n\}$ is a basis of V^* , a basis of $\wedge^p V^*$ is given by the following $\binom{n}{p}$ vectors

$$\{\theta^{a_1} \wedge \dots \wedge \theta^{a_p} \mid 1 \leq a_1 < a_2 < \dots < a_p \leq n\}. \quad (9)$$

An expansion of $\alpha \in \wedge^p V^*$ in this basis is written as follows

$$\alpha =: \frac{1}{p!} \alpha_{a_1 \dots a_p} \theta^{a_1} \wedge \dots \wedge \theta^{a_p}, \quad (10)$$

using standard summation convention and where the coefficients $\alpha_{a_1 \dots a_p}$ are totally antisymmetric in all indices. On the level of coefficients, (6) reads

$$(\alpha \wedge \beta)_{a_1 \dots a_{p+q}} = \frac{(p+q)!}{p!q!} \alpha_{[a_1 \dots a_p} \beta_{a_{p+1} \dots a_{p+q}]}, \quad (11)$$

where square brackets denote total antisymmetrisation in all indices enclosed:

$$\alpha_{[a_1 \dots a_p]} := \frac{1}{p!} \sum_{\sigma \in S_p} \text{sign}(\sigma) \alpha_{a_{\sigma(1)} \dots a_{\sigma(p)}}. \quad (12)$$

2 Inner products

Every non-degenerate bilinear form $\eta : V \times V \rightarrow \mathbb{R}$ on a vector space V defines an isomorphism $\eta_{\downarrow} : V \rightarrow V^*$ to its dual space V^* via the requirement $\eta_{\downarrow}(v)(w) := \eta(v, w)$ for all $v, w \in V$; in short, $v \mapsto \eta_{\downarrow}(v) := \eta(v, \cdot)$. Its inverse map is $\eta_{\uparrow} : V^* \rightarrow V$, $\eta_{\uparrow} := (\eta_{\downarrow})^{-1}$, which in turn defines a non-degenerate bilinear form on the dual space, $\eta^{-1} : V^* \times V^* \rightarrow \mathbb{R}$, via the requirement $\eta^{-1}(\alpha, \beta) := \alpha(\eta_{\uparrow}(\beta))$ for all $\alpha, \beta \in V^*$. On component-level this reads as follows: Let $\{e_a \mid 1 \leq a \leq n\}$ be a basis of V and $\{\theta^a \mid 1 \leq a \leq n\}$ its dual basis of V^* , so that $\theta^a(e_b) = \delta_b^a$. Then, writing $v = v^a e_a$, we get $\eta_{\downarrow}(v) = v_b \theta^b$ with

$$v_b := v^a \eta_{ab} \quad (13)$$

and $\eta_{ab} := \eta(e_a, e_b)$. Similarly, writing $\alpha = \alpha_a \theta^a$, we get $\eta_{\uparrow}(\alpha) = \alpha^a e_a$ with

$$\alpha^a := \eta^{ab} \alpha_b \quad (14)$$

and $\eta^{ab} := \eta^{-1}(\theta^a, \theta^b)$. Note that in (13) it is the *first* index on η_{ab} that is contracted with v_a whereas in (14) it is the *second* index on η^{ab} that is contracted with α_b . This is important for consistency in case η is not symmetric.

The previous equations imply

$$\eta^{ac}\eta_{bc} = \eta^{ca}\eta_{cb} = \delta_b^a \quad (15)$$

and

$$\eta^{ab} = \eta^{ac}\eta^{bd}\eta_{cd} \quad (16a)$$

$$\eta_{ab} = \eta^{cd}\eta_{ca}\eta_{db}. \quad (16b)$$

This explains why η_{\uparrow} and η_{\downarrow} are called the operations of “index-raising” and “index lowering”. Sometimes the images of η_{\uparrow} and η_{\downarrow} are indicated by the musical symbols \sharp (sharp) and \flat (flat) respectively, i.e., one writes $\eta_{\uparrow}(\alpha) = \alpha^{\sharp}$ and $\eta_{\downarrow}(v) = v^{\flat}$, which makes sense as long as the bilinear form η with respect to which these maps are defined is self understood. We shall also employ this notation.

We stress once more that up to this point we did not assume η to be symmetric, so that all formulae apply generally. In particular, they will apply to antisymmetric η which occur in spinor calculus. However, for the rest of these supplementary notes we will assume η to be symmetric.

The symmetric inner products on V and V^* naturally extend to symmetric inner product on tensor-product spaces, just by taking products slotwise. In particular, we have on $T^p V^*$

$$\langle \alpha_1 \otimes \cdots \otimes \alpha_p, \beta_1 \otimes \cdots \otimes \beta_p \rangle := \prod_{a=1}^p \eta^{-1}(\alpha_a, \beta_a) \quad (17)$$

and bilinear extension:

$$\langle \alpha_{a_1 \dots a_p} \theta^{a_1} \otimes \cdots \otimes \theta^{a_p}, \beta_{b_1 \dots b_p} \theta^{b_1} \otimes \cdots \otimes \theta^{b_p} \rangle = \alpha_{a_1 \dots a_p} \beta^{a_1 \dots a_p}. \quad (18)$$

On each subspace $\bigwedge^p V^* \subset T^p V^*$ we have

$$\langle \alpha_1 \wedge \cdots \wedge \alpha_p, \beta_1 \wedge \cdots \wedge \beta_p \rangle := p! \sum_{\sigma \in S_p} \text{sign}(\sigma) \prod_{a=1}^p \eta(\alpha_a, \beta_{\sigma(a)}) \quad (19)$$

and hence

$$\left\langle \frac{1}{p!} \alpha_{a_1 \dots a_p} \theta^{a_1} \wedge \cdots \wedge \theta^{a_p}, \frac{1}{p!} \beta_{b_1 \dots b_p} \theta^{b_1} \wedge \cdots \wedge \theta^{b_p} \right\rangle = \alpha_{a_1 \dots a_p} \beta^{a_1 \dots a_p}. \quad (20)$$

In the totally antisymmetric case it is sometimes more convenient to renormalise this product in a p -dependent fashion. One sets

$$\langle \cdot, \cdot \rangle_{\text{norm}} |_{\wedge^p V^*} := \frac{1}{p!} \langle \cdot, \cdot \rangle |_{\wedge^p V^*} \quad (21)$$

so that

$$\left\langle \frac{1}{p!} \alpha_{a_1 \dots a_p} \theta^{a_1} \wedge \dots \wedge \theta^{a_p}, \frac{1}{p!} \beta_{b_1 \dots b_p} \theta^{b_1} \wedge \dots \wedge \theta^{b_p} \right\rangle_{\text{norm}} = \frac{1}{p!} \alpha_{a_1 \dots a_p} \beta^{a_1 \dots a_p}. \quad (22)$$

3 Hodge duality

Given a choice o of an orientation of V^* (e.g. induced by an orientation of V), there is a unique top-form $\varepsilon \in \wedge^n V^*$ (i.e. a *volume form* for V), associated with the triple (V^*, η^{-1}, o) , given by

$$\varepsilon := \theta^1 \wedge \dots \wedge \theta^n, \quad (23)$$

where $\{\theta^1, \dots, \theta^n\}$ is any η^{-1} -orthonormal Basis of V^* in the orientation class o . The *Hodge duality* map at level $0 \leq p \leq n$ is a linear isomorphism

$$\star_p : \wedge^p V^* \rightarrow \wedge^{n-p} V^*, \quad (24a)$$

defined implicitly by

$$\alpha \wedge \star_p \beta = \varepsilon \langle \alpha, \beta \rangle_{\text{norm}}. \quad (24b)$$

This means that the image of $\beta \in \wedge^p V^*$ under \star_p in $\wedge^{n-p} V^*$ is defined by the requirement that (24b) holds true for all $\alpha \in \wedge^p V^*$. Linearity is immediate and uniqueness of \star_p follows from the fact that if $\lambda \in \wedge^{n-p} V^*$ and $\alpha \wedge \lambda = 0$ for all $\alpha \in \wedge^p V^*$, then $\lambda = 0$. To show existence it is sufficient to define \star_p on basis vectors. Since (24b) is also linear in α it is sufficient to verify (24b) if α runs through all basis vectors.

From now on we shall follow standard practice and drop the subscript p on \star , supposing that this will not cause confusion.

Let $\{e_1, \dots, e_n\}$ be a basis of V and $\{\theta^1, \dots, \theta^n\}$ its dual basis of V^* ; i.e. $\theta^a(e_b) = \delta_b^a$. Let further $\{\theta_1, \dots, \theta_n\}$ be the basis of V^* given by the image of $\{e_1, \dots, e_n\}$ under η_\downarrow , i.e. $\theta_a = \eta_{ab} \theta^b$. Then, on the basis $\{\theta_{a_1} \wedge \dots \wedge \theta_{a_p} \mid 1 \leq a_1 < a_2 < \dots < a_p \leq n\}$ of $\wedge^p V^*$ the map \star has the simple form

$$\star(\theta_{b_1} \wedge \dots \wedge \theta_{b_p}) = \frac{1}{(n-p)!} \varepsilon_{b_1 \dots b_p a_{p+1} \dots a_n} \theta^{a_{p+1}} \wedge \dots \wedge \theta^{a_n}. \quad (25)$$

This is proven by merely checking (24b) for $\alpha = \theta^{a_1} \wedge \dots \wedge \theta^{a_p}$ and $\beta = \theta_{b_1} \wedge \dots \wedge \theta_{b_p}$. Instead of (25) we can write

$$\begin{aligned} \star(\theta^{a_1} \wedge \dots \wedge \theta^{a_p}) &= \frac{1}{(n-p)!} \eta^{a_1 b_1} \dots \eta^{a_p b_p} \varepsilon_{b_1 \dots b_p b_{p+1} \dots b_n} \theta^{b_{p+1}} \wedge \dots \wedge \theta^{b_n} \\ &= \frac{1}{(n-p)!} \varepsilon^{a_1 \dots a_p a_{p+1} \dots a_n} \theta^{a_{p+1}} \wedge \dots \wedge \theta^{a_n}, \end{aligned} \quad (26)$$

which makes explicit the dependence on ε and η .

If $\alpha = \frac{1}{p!} \alpha_{a_1 \dots a_p} \theta^{a_1} \wedge \dots \wedge \theta^{a_p}$, then $\star \alpha = \frac{1}{(n-p)!} (\star \alpha)_{b_1 \dots b_{n-p}} \theta^{b_1} \wedge \dots \wedge \theta^{b_{n-p}}$, where

$$(\star \alpha)_{b_1 \dots b_{n-p}} = \frac{1}{p!} \alpha_{a_1 \dots a_p} \varepsilon^{a_1 \dots a_p}_{b_1 \dots b_{n-p}}. \quad (27)$$

This gives the familiar expression of Hodge duality in component language. Note that on component level the first (rather than last) p indices are contracted.

Applying \star twice (i.e. actually $\star_{(n-p)} \circ \star_p$) leads to the following self-map of $\wedge^p V^*$:

$$\begin{aligned} & \star(\star(\theta^{a_1} \wedge \dots \wedge \theta^{a_p})) \\ &= \frac{1}{p!(n-p)!} \varepsilon^{a_1 \dots a_p}_{a_{p+1} \dots a_n} \varepsilon^{a_{p+1} \dots a_n}_{b_1 \dots b_p} \theta^{b_1} \wedge \dots \wedge \theta^{b_p} \\ &= \frac{(-1)^{p(n-p)}}{p!(n-p)!} \varepsilon^{a_1 \dots a_p a_{p+1} \dots a_n} \varepsilon_{b_1 \dots b_p a_{p+1} \dots a_n} \theta^{b_1} \wedge \dots \wedge \theta^{b_p} \\ &= (-1)^{p(n-p)} \langle \varepsilon, \varepsilon \rangle_{\text{norm}} \theta^{a_1} \wedge \dots \wedge \theta^{a_p}. \end{aligned} \quad (28)$$

Note that

$$\langle \varepsilon, \varepsilon \rangle_{\text{norm}} = \frac{1}{n!} \eta^{a_1 b_1} \dots \eta^{a_n b_n} \varepsilon_{a_1 \dots a_n} \varepsilon_{b_1 \dots b_n} = (\varepsilon_{12 \dots n})^2 / \det\{\eta(e_a, e_b)\}. \quad (29)$$

This formula holds for any volume form ε in the definition (24b), independent of whether or not it is related to η .

Since the right-hand side of (24b) is symmetric under the exchange $\alpha \leftrightarrow \beta$, so must be the left-hand side. Using (28) we get

$$\begin{aligned} \langle \alpha, \beta \rangle_{\text{norm}} \varepsilon &= \alpha \wedge \star \beta = \beta \wedge \star \alpha = (-1)^{p(n-p)} \star \alpha \wedge \beta \\ &= \langle \varepsilon, \varepsilon \rangle_{\text{norm}}^{-1} \star \alpha \wedge \star \star \beta = \langle \varepsilon, \varepsilon \rangle_{\text{norm}}^{-1} \langle \star \alpha, \star \beta \rangle_{\text{norm}} \varepsilon, \end{aligned} \quad (30)$$

hence

$$\langle \star \alpha, \star \beta \rangle_{\text{norm}} = \langle \varepsilon, \varepsilon \rangle_{\text{norm}} \langle \alpha, \beta \rangle_{\text{norm}}. \quad (31)$$

From this and (28)) it follows for $\alpha \in \wedge^p V^*$ and $\beta \in \wedge^{n-p} V^*$, that

$$\langle \alpha, \star \beta \rangle_{\text{norm}} = \langle \varepsilon, \varepsilon \rangle_{\text{norm}}^{-1} \langle \star \alpha, \star \star \beta \rangle_{\text{norm}} = (-1)^{p(n-p)} \langle \star \alpha, \beta \rangle_{\text{norm}}. \quad (32)$$

This shows that the adjoint map of \star relative to $\langle \cdot, \cdot \rangle_{\text{norm}}$ is $(-1)^{p(n-p)} \star$.

Formulae (28), (30)(31), and (32) are valid for general ε in the definition (24b). If we chose ε in the way we did, namely as the unique volume form that assigns unit volume to an oriented orthonormal frame, as does (23), then we have

$$\langle \varepsilon, \varepsilon \rangle_{\text{norm}} = (-1)^{n_-} \quad (33)$$

where n_- is the maximal dimension of subspaces in V restricted to which η is negative definite; i.e. η is of signature (n_+, n_-) . Equation (31) then shows

that \star is an isometry for even n_- and an anti-isometry for odd n_- (as for Lorentzian η in any dimension).

Finally we note the following useful formula: If $v \in V$ let $i_v : T^p V^* \rightarrow T^{p-1} V^*$ the map which inserts v into the first tensor factor. It restricts to a map $i_v : \wedge^p V^* \rightarrow \wedge^{p-1} V^*$. Then, for any $\alpha \in \wedge^p V^*$, we have

$$i_v \star \alpha = \star(\alpha \wedge v^\flat). \quad (34)$$

where $v^\flat := \eta_\downarrow(v)$. It suffices to prove this for basis elements $v = e_a$ of V and $\alpha = \theta^{a_1} \wedge \cdots \wedge \theta^{a_p}$ of $\wedge^p V^*$, which is almost immediate using (26).